Knapsack Problem for Perishable Inventories

Darina Graczová*, Peter Jacko

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products

- why perishable?
 - perishable goods food, change in fashion, design

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products

- why perishable?
 - perishable goods food, change in fashion, design
- how to sell such products before their deadlines?
 - lower the price of those products

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products

- why perishable?
 - perishable goods food, change in fashion, design
- how to sell such products before their deadlines?
 - lower the price of those products or
 - promote those products

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Problem



who what to do limits what

priority

boy go camping bag clothes and other camping stuff most necessary things retailer sell the inventories promotion space (shelf, room) products (inventories)

maximization of the revenue

- formulate the problem in the framework of Markov decision processes (MDP) with a sample-path knapsack capacity constraint
- formulate the KPPIs problem
- apply Whittle relaxation and Lagrangian method, and decompose the problem
- ! derive the index
- ! introduce *Index Knapsack* heuristic and its performance and show the near-optimality

Knapsack Properties

- *I* perishable products $i \in \mathcal{I}$
- *K_i* units of each product *i*
- *H* planning horizon, $H \leq \infty$
- C knapsack volume, $\sum_{i} W_i > C$, where W_i is volume of every unit of product i

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product i

- T_i product's lifetime, $T_i \in [1, H]$
- $R_i > 0$ revenue
- $\alpha_i R_i$ salvage revenue, where $\alpha_i \leq 1$

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- β discount factor

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Only a single unit of each product can be demanded by the customers in one period. The demand is formalized by Bernoulli arrivals of the customers.

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probability of selling:

- $1 p_i$ a unit of product *i* is sold when promoted in a period,
- $1 q_i$ a unit of product *i* is sold when not promoted in a period.

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probability of selling:

- $1 p_i$ a unit of product *i* is sold when promoted in a period,
- $1 q_i$ a unit of product *i* is sold when not promoted in a period.
- \rightarrow increase: $q_i p_i > 0$

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Formulation of MDP Model of Perishable Inventory with Bernoulli Demand

• state
$$n = (t, k)$$
, where

t represents the number of remaining periods before the deadline, and

k represents the remaining inventory;

state $\lfloor n = 0 \rfloor$ - product is perished or there are no units left

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• action a

1 to promote a unit

0 not to promote;

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• action a

1 to promote a unit

- 0 not to promote;
- expected one-period capacity occupation:

$$W_{i,n}^a := egin{cases} W_i & a = 1 \ 0 & a = 0 \end{cases}$$

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one-period transition probability matrix P_i^{1|N_i} under promoting (for K_i = 2)

	0	(1, 1)		$(T_i-1,1)$	$(T_i, 1)$	(1, 2)		$(T_i - 1, 2)$	
0	, 1	0	0	0	0	0	0	0	0
(1, 1)	1	0	0	0	0	0	0	0	0)
(2, 1)	$1 - p_i$	Pi	0	0	0	0	0	0	0
:	:	0	·	0	0	0	0	0	0
$(T_i, 1)$	$1 - p_i$	0	0	Pi	0	0	0	0	0
(1, 2)	1	0	0	0	0	0	0	0	0
(2, 2)	0	$1 - p_{i}$	0	0	0	Pi	0	0	0
:			۰.	0	0	0	·.	0	
$(T_i, 2)$		0	0	$1 - p_i$	0	0	0	D Pi	0)

one-period transition probability matrix P_i^{1|N_i} under promoting (for K_i = 2)

	0	(1, 1)		$(T_i-1,1)$	$(T_i, 1)$	(1, 2)		$(T_i - 1, 2)$	
0	1	0	0	0	0	0	0	0	0
(1, 1) (2, 1)	$\begin{pmatrix} 1\\ 1-\rho_i \end{pmatrix}$	0 Pi	0 0	0 0	0 0	0 0	0 0	0 0	0 0
$(T_i, 1)$	$\begin{array}{c} \vdots \\ 1 - p_i \end{array}$	0 0	·. 0	0 Pi	0 0	0 0	0 0	0 0	0 0
(1, 2) (2, 2)	1 0	0 1 — p _i	0 0	0 0	0 0	0 Pi	0 0	0 0	0 0
(<i>T_i</i> , 2)	0	0	·. 0	0 $1 - p_i$	0 0	0 0	·. 0	0 Pi	0 0

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	0	(1, 1)		$(T_i - 1, 1)$	$(T_i, 1)$	(1, 2)		$(T_i - 1, 2)$	$(T_i, 2)$
0	_ 1	0	0	0	0	0	0	0	0
(1, 1) (2, 1)	$\begin{vmatrix} 1\\ 1-p_i \end{vmatrix}$	0 Pi	0 0	0 0	0 0	0 0	0 0	0 0	0 0
$(T_i, 1)$	$\begin{array}{c} \vdots \\ 1 - p_i \end{array}$	0 0	·. 0	0 Pi	0 0	0 0	0 0	0 0	0
(1, 2) (2, 2)	1 0	0 1 — p _i	0 0	0 0	0 0	0 Pi	0 0	0 0	0 0
(<i>T_i</i> , 2)	0	0 0	0	0 1 — p _i	0 0	0 0	·. 0	0 Pi	0 0

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	0	(1, 1)		$(T_i - 1, 1)$	$(T_i, 1)$	(1, 2)		$(T_i - 1, 2)$	(<i>T_i</i> , 2)
0	_ 1	0	0	0	0	0	0	0	0
(1, 1) (2, 1)	$\begin{vmatrix} 1\\ 1-p_i \end{vmatrix}$	0 Pi	0 0	0 0	0 0	0 0	0 0	0 0	0 0
$(T_i, 1)$: 1 – p _i	0 0	0	0 Pi	0 0	0	0 0	0 0	0
(1, 2) (2, 2)	1 0	0 1 — p _i	0 0	0 0	0 0	0 Pi	0 0	0 0	0 0
(<i>T_i</i> , 2)	0	0 0	·. 0	0 1 — p _i	0 0	0 0	·. 0	0 Pi	0 0

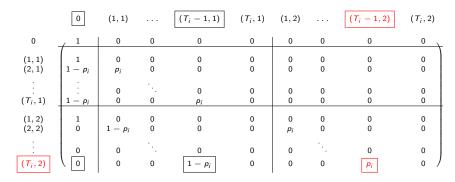
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	0	(1, 1)		$(T_i - 1, 1)$	$(T_i, 1)$	(1, 2)		$(T_i - 1, 2)$	(<i>T_i</i> , 2)
0	_ 1	0	0	0	0	0	0	0	0
(1, 1)	$\begin{vmatrix} 1\\ 1-p_i \end{vmatrix}$	0	0	0	0	0	0	0	0
(2, 1)		Pi	0	0	0	0	0	0	0
$(T_i, 1)$:	0	·	0	0	0	0	0	0
	1 — p _i	0	0	Pi	0	0	0	0	0
(1, 2)	1	0	0	0	0	0	0	0	0
(2, 2)	0	1 — p _i	0	0	0	Pi	0	0	0
(<i>T_i</i> , 2)	0	0 0	· 0	0 1 — p _i	0 0	0 0	0	0 Pi	0 0

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	0	(1, 1)		$(T_i-1,1)$	$(T_i, 1)$	(1, 2)		$(T_i - 1, 2)$	$(T_i, 2)$
0	_ 1	0	0	0	0	0	0	0	0
(1, 1)	$\begin{vmatrix} 1\\ 1-p_i \end{vmatrix}$	0	0	0	0	0	0	0	0
(2, 1)		Pi	0	0	0	0	0	0	0
$(T_i, 1)$:	0		0	0	0	0	0	0
	1 – p _i	0	0	Pi	0	0	0	0	0
(1, 2)	1	0	0	0	0	0	0	0	0
(2, 2)	0	1 — p _i	0	0	0	Pi	0	0	0
(<i>T_i</i> , 2)	0	0 0	0	$\frac{0}{1-p_i}$	0 0	0 0	0	0 Pi	0 0

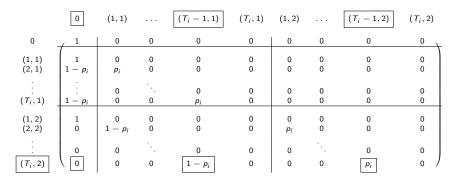


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one-period transition probability matrix P_i^{1|N_i} under promoting (for K_i = 2)



 $\mathbf{P}_{\mathbf{i}}^{\mathbf{0}|\mathcal{N}_{\mathbf{i}}}$ by substituting p_i by q_i in $\mathbf{P}_{\mathbf{i}}^{\mathbf{1}|\mathcal{N}_{\mathbf{i}}}$

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• one-period transition probability matrix $\mathbf{P}_{i}^{1|\mathcal{N}_{i}}$ under promoting (for $K_{i} = 2$)

	0	(1, 1)		$(T_i-1,1)$	$(T_i, 1)$	(1, 2)		$(T_i - 1, 2)$	$(T_i, 2)$
0	, 1	0	0	0	0	0	0	0	0 \
(1, 1)	1	0	0	0	0	0	0	0	0
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:	<u>:</u>		· .				_		
	· ·	0	•	0	0	0	0	0	0
$(T_{i}, 1)$	$1 - p_i$	0	0	Pi	0	0	0	0	0
(1, 2)	1	0	0	0	0	0	0	0	0
(2, 2)	0	$1 - p_i$	0	0	0	Pi	0	0	0
	0	0	· · ·	0	0	0	·.	0	0
$(T_i, 2)$	\ ₀	0	0	$1 - p_{i}$	0	0	0	Pi	0 /

• expected one-period revenue:

$$egin{aligned} R_{i,(t,k)}^1 &:= R_i(1-p_i) \ R_{i,(1,k)}^1 &:= R_i(1-p_i) + eta lpha_i R_i(p_i+k-1) \ R_{i,0}^1 &:= 0 \end{aligned}$$

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KPPIs, Relaxation and Decomposition

$$\max_{\pi \in \Pi_{\mathbf{X},\mathbf{a}}} \mathbb{E}_{0}^{\pi} \left[\sum_{i \in \mathcal{I}} \sum_{s=0}^{H} \beta^{s} R_{i,X_{i}(s)}^{\mathbf{a}_{i}(s)} \right]$$

subject to
$$\sum_{i \in \mathcal{I}} W_{i,X_{i}(s)}^{\mathbf{a}_{i}(s)} \leq C \text{ at each time period } s \in \mathcal{H},$$

where $\mathbf{X}(\cdot) := (X_i(\cdot))_{i \in \mathcal{I}}$ is the joint state-process; and $\mathbf{a}(\cdot) := (a_i(\cdot))_{i \in \mathcal{I}}$ is the joint action-process.

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one product parametric optimization subproblem:

$$\max_{\pi \in \Pi_{X_i,a_i}} \mathbb{E}_0^{\pi} \left[\sum_{s=0}^H \beta^s R_{X_i(s)}^{a_i(s)} \right] - \nu \mathbb{E}_0^{\pi} \left[\sum_{s=0}^H \beta^s W_{X_i(s)}^{a_i(s)} \right],$$

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KPPIs, Relaxation and Decomposition

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Definition (Indexability).

We say that ν -parameterized inventory is *indexable*, if there exist unique values $-\infty \leq \nu_n \leq \infty$ for all $n \in \mathcal{N}$ such that the following holds:

- **1** if $\nu_n \geq \nu$, then it is optimal to promote in state *n*, and
- **2** if $\nu_n \leq \nu$, then it is optimal not to promote in state *n*.

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- **2** if $\nu_n \leq \nu$, then it is optimal not to promote in state *n*.
 - MDP theory \rightarrow existence of an optimal policy (stationary, deterministic, independent on initial state)
 - $\mathcal{S}(\nu)$ active set representing a stationary policy, set of all states with action 1

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Analytical approach

provably indexable products

Numerical approach

numerical testing of indexability

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Provably Indexable Products

Assumption

$$\ \, \mathbf{0} \ \ \, \mathbf{q}-\mathbf{p} > \mathbf{0}, \ \alpha \leq \mathbf{0} \ \, \text{for} \ \, \beta \leq 1.$$

2 family \mathcal{F}_1 of active sets

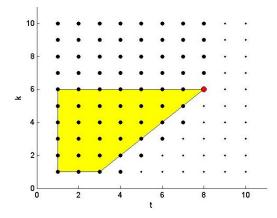


Figure: Behavior of added states (S filled area).

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Knapsack Problem for Perishable Inventories

If for every ν there is an optimal active set that belongs to \mathcal{F}_1 , then the product is indexable, and the index value for its state $(t, k) \in \mathcal{T} \times \mathcal{K}$ is

$$\nu_{(t,k)}^{*} = \begin{cases} \frac{R}{W}(1-p) \left[1 - \frac{1-q+(q-p)\beta^{t}\alpha}{1-p} \right] & t \leq k \\ \frac{R}{W}(1-p) \left[1 - \frac{1-q+\beta^{t}\alpha(q-p)p^{t-k}\sum_{i=0}^{k-1} {\binom{t-k-1+i}{i}(1-p)^{i}}}{1-p-(q-p)\beta^{k}(1-p)^{k}\sum_{i=0}^{t-k-1} {\binom{k-1+i}{i}(\beta p)^{i}}} \right] & t > k \end{cases}$$

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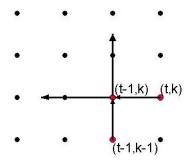
• fast recursive computation: $\mathcal{O}(TK)$

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the monotonicity properties of index are

(i)
$$\nu_{(t-1,k)}^* \ge \nu_{(t,k)}^*$$

 $\forall k \ge 1, \forall t > 1$
(ii) $\nu_{(t,k-1)}^* \le \nu_{(t,k)}^*$
 $\forall k > 1, \forall t \ge 1$
(iii) $\nu_{(s,l)}^* \ge \nu_{(t,k)}^*$
 $\forall l \ge k, \forall s \le t$



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Numerical Testing

• problem is indexable for all products parameters

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Numerical Testing

• problem is indexable for all products parameters

• for
$$\alpha \leq 0$$
 and $\beta \leq 1$ and for $\alpha \leq 1$ and $\beta = 1$

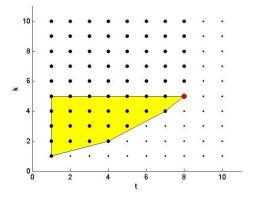


Figure: Behavior of added states (S filled area).

Index Rule for KPPIs

procedure

- to use the index as a price $v_i^{(s)} := W_i \nu_{i,X_i(s)}^*$, in every $s \in [0,H]$
- to solve the following knapsack problem

$$\max_{\mathbf{z}} \sum_{i \in \mathcal{I}} z_i^{(s)} v_i^{(s)}$$

s.t.
$$\sum_{i \in \mathcal{I}} z_i^{(s)} W_i \le C$$
$$z_i^{(s)} \in \{0, 1\} \text{ for all } i \in \mathcal{I}$$
$$\mathbf{z}_i^{(s)} = (z_i^{(s)} : i \in \mathcal{I}) \text{ is vector of binary decision}$$

where $\mathbf{z}^{(s)} = (z_i^{(s)} : i \in \mathcal{I})$ is vector of binary decision variables.

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Index Rule for KPPIs

procedure

- to use the index as a price $v_i^{(s)} := W_i v_{i,X_i(s)}^*$, in every $s \in [0, H]$
- to solve the following knapsack problem

$$\begin{split} \max_{\mathbf{z}} \sum_{i \in \mathcal{I}} z_i^{(s)} v_i^{(s)} \\ \text{s.t.} \quad \sum_{i \in \mathcal{I}} z_i^{(s)} W_i \leq C \\ z_i^{(s)} \in \{0, 1\} \text{ for all } i \in \mathcal{I} \end{split}$$
(KP)

where $\mathbf{z}^{(s)} = (z_i^{(s)} : i \in \mathcal{I})$ is vector of binary decision variables.

(IK) Index-Knapsack heuristic: Calculate the prices v_i and then solve the knapsack problem optimally.

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Knapsack Problem for Perishable Inventories

solving KPPIs

- optimally $\rightarrow D^{\max}$
- $\, \bullet \,$ by employing the heuristic $\rightarrow D^{\pi}$

adjusted relative suboptimality gap

$$ext{arsg}(\pi) = rac{D^{ ext{max}} - D^{\pi}}{D^{ ext{max}} - D^{ ext{min}}},$$

where $0 \leq \operatorname{arsg}(\pi) \leq 1$

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Results for Index-Knapsack heuristic (analytically computed index)

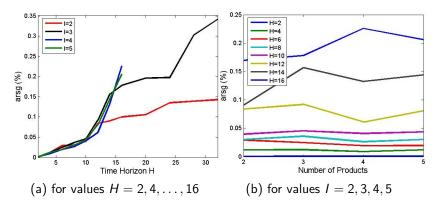


Figure: Mean adjusted relative suboptimality gap for IK heuristic with analytically computed index.

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- formulation of the problem as MDP
- discussion of the optimal policy from analytical and numerical point of view
- derivation of the index
- showing the near-optimality of IK heuristic

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Thank you for your attention.

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