Nearly-Optimal Index Rules for Some Non-work-conserving Systems

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Talk Outline

- Resource allocation MDP framework
- Decomposition and indexability
- Index rules for multi-class -/Geo/M queues
 - $\triangleright c\mu$ -rule
 - $\triangleright c(\mu \theta)/\theta$ -rule (for abandonments)
 - potential improvement rule (for time-varying rates)
 a new rule (for time-varying and abandonments)
- Performance evaluation in systems with arrivals

Resource Allocation Problem (RAP)

- Stochastic and dynamic
- There is a number of independent competitors
- Constraint: resource capacity M at any time
- Objective: maximize expected "reward"
- Captures the exploitation vs. exploration trade-off
 always exploiting (being myopic) is not optimal
 always exploring (being utopic) is not optimal
- This is a model of learning by doing!

MDP Framework

- Markov Decision Processes / restless bandits
- Discrete time model (t = 0, 1, 2, ...)
- Job $k \in \mathcal{K}$ is defined by
 - ▷ states N_k, actions A := {0,1} = {'wait', 'serve'}
 ▷ expected one-period capacity consumption W^a_k
 ▷ expected one-period reward R^a_k
 ▷ one-period transition probability matrix P^a_k
- State process $X_k(t) \in \mathcal{N}_k$
- Action process $a_k(t) \in \mathcal{A}$ to be decided

Resource Allocation Problem

• Formulation under the β -discounted criterion:

$$\begin{split} \max_{\pi \in \Pi} \sum_{k \in \mathcal{K}} \mathbb{E}^{\pi} \left[\sum_{t=0}^{\infty} \beta^{t} R_{k,X_{k}(t)}^{a_{k}(t)} \right] \\ \text{subject to} \quad \sum_{k \in \mathcal{K}} W_{k,X_{k}(t)}^{a_{k}(t)} = W, \quad \text{ for all } t = 0, 1, 2, \dots \end{split}$$

- Analogously under the time-average criterion
- This problem is PSPACE-hard (Papad. & Tsits. 1999)
 intractable to solve exactly by Dynamic Programming
 instead, we relax and decompose the problem

Relaxations and Decomposition

- 1. Whittle's (1988): Serve W jobs in expectation
 - infinite number of constraints is replaced by one
 sort of perfect market assumption
- 2. Lagrangian: Pay cost *ν* for using the server
 ▷ the constraint is moved into the objective
- Decomposes due to user independence into single-user parametric subproblems
 - solved by identifying the efficiency frontier
 - \triangleright indexability \approx threshold policies are optimal
 - ▷ math + art = characterize index values

Index Rules

- Assign an index value to each state of each user
- We are concerned with the following rule
 - > at each time, be greedy: serve jobs with highest current index values
- In some problems it is optimal
 - *cµ*-rule (Cox & Smith '61): job sequencing
 ► Gittins index rule ('72): multi-armed bandit problem
 - ▷ Klimov index rule ('74): M/G/1 model w/ feedback
- Experiments and simulations suggest that it gives a nearly-optimal solution to RAP

Warm-up: Job Sequencing Problem

- Find a serving sequence minimizing the total cost of waiting of jobs $k \in \mathcal{K}$
 - $\triangleright c_k = \text{cost of waiting for job } k$
 - $\triangleright \mu_k =$ completion probability for job k
- $\mathcal{N}_k := \{\text{`completed', `waiting'}, \mathcal{A} := \{\text{`serve', `wait'}\}$
- Expected one-period capacity consumption

Warm-up: Job Sequencing Problem

Expected one-period reward

$$\begin{array}{ll} R_{k,\text{`completed'}}^{\text{`serve'}} := 0, & R_{k,\text{`waiting'}}^{\text{`serve'}} := -c_k(1 - \mu_k), \\ R_{k,\text{`completed'}}^{\text{`wait'}} := 0, & R_{k,\text{`waiting'}}^{\text{`wait'}} := -c_k; \end{array}$$

One-period transition probability matrices



- Find a serving sequence minimizing the total cost of waiting and abandonment penalties of jobs $k \in \mathcal{K}$
 - $\triangleright c_k = \text{cost of waiting for job } k$
 - $\triangleright \mu_k =$ completion probability for job k
 - $\triangleright d_k = abandonment penalty for job k$
 - $\triangleright \ \theta_k = \text{abandonment} \ \text{probability} \ \text{for job} \ k$
- $\mathcal{N}_k := \{\text{`completed or abandoned', `waiting'}\}$
- $\mathcal{A} := \{$ 'wait', 'serve' $\}$
- Expected one-period capacity consumption ...

Expected one-period reward

$$\begin{split} R_{k,\text{`completed or abandoned'}}^{\text{`serve'}} &:= 0, \quad R_{k,\text{`waiting'}}^{\text{`serve'}} &:= -c_k(1 - \mu_k), \\ R_{k,\text{`completed or abandoned'}}^{\text{`wait'}} &:= 0, \quad R_{k,\text{`waiting'}}^{\text{`wait'}} &:= -c_k(1 - \theta_k) - d_k \theta_k; \end{split}$$

One-period transition probability matrices

$$oldsymbol{P}_k^{ ext{'serve'}} \coloneqq rac{ ext{'compl. or ab.'}}{ ext{'waiting'}} \left(egin{array}{c} 1 & 0 \ \mu_k & 1 - \mu_k \end{array}
ight) \ oldsymbol{P}_k^{ ext{'wait'}} \coloneqq rac{ ext{'compl. or ab.'}}{ ext{'waiting'}} \left(egin{array}{c} 1 & 0 \ \mu_k & 1 - \mu_k \end{array}
ight) \ oldsymbol{compl. or ab.'} \left(egin{array}{c} 1 & 0 \ \mu_k & 1 - \mu_k \end{array}
ight) \ oldsymbol{vaiting'} \left(egin{array}{c} 1 & 0 \ \theta_k & 1 - \theta_k \end{array}
ight) \end{array}$$

• Under discounted criterion:

$$\nu_{k,\text{'waiting'}}^{\text{AJN}} = \frac{c_k(\mu_k - \theta_k) + d_k\theta_k(1 - \beta + \beta\mu_k)}{1 - \beta + \beta\theta_k}$$
$$\nu_{k,\text{'completed or abandoned'}}^{\text{AJN}} = 0$$

Under time-average criterion:

$$\nu_{k,\text{`waiting'}}^{\text{AJN}} = \frac{c_k(\mu_k - \theta_k) + d_k\mu_k\theta_k}{\theta_k}$$
$$\nu_{k,\text{`completed or abandoned'}}^{\text{AJN}} = 0$$

• Ayesta, J. & Novak (2011), IEEE INFOCOM

• Two classes: $\mu_1=0.4$, $\mu_2=0.22$, $heta_1=0.1$, $heta_2=0.2$ and $c_1=d_1=d_2=\lambda_1=\lambda_2=1$



- Job/user $k \in \mathcal{K}$ is defined by
 - c_k = cost of waiting for job k
 q_{k,n} = probability to move to condition n
 μ_{k,n} = completion probability for job k under condition n (ordered: μ_{k,n} ≤ μ_{k,n+1})
- Find a serving sequence minimizing the total cost of waiting of jobs $k \in \mathcal{K}$

•
$$\mathcal{N}_k := \{0, 1, 2, \dots, N_k\}$$
, $\mathcal{A} := \{$ 'wait', 'serve' $\}$

 $\bullet \ 0 = \ \mbox{`completed'}$; $n = \ \mbox{`waiting'}$ and condition is n

• Expected one-period reward

$$\begin{split} R_{k,0}^{\text{`serve'}} &:= 0, & R_{k,n}^{\text{`serve'}} &:= -c_k (1 - \mu_{k,n}), \\ R_{k,0}^{\text{`wait'}} &:= 0, & R_{k,n}^{\text{`wait'}} &:= -c_k; \end{split}$$

• One-period transition probability matrices

- Potential improvement (opportunistic) index
- Under discounted criterion:

$$\nu_{k,n}^{\mathsf{PI}} = \frac{c_k \mu_{k,n}}{(1-\beta) + \beta \sum_{m>n} q_{k,m} (\mu_{k,m} - \mu_{k,n})}$$

• Under time-average criterion:

$$\nu_{k,n}^{\mathsf{PI}} = \frac{c_k \mu_{k,n}}{\sum\limits_{m>n} q_{k,m}(\mu_{k,m} - \mu_{k,n})} \text{ for } n \neq N_k, \qquad \nu_{k,N_k}^{\mathsf{PI}} = \infty$$

- \triangleright tie-breaking if in the best state: $c_k \mu_{k,N_k}$
- Ayesta, Erausquin & J. (2010), IFIP Performance

• Varied λ_1 so that ϱ varies from 0.5 to 1



- \bullet Job/user $k \in \mathcal{K}$ is defined by
 - $\triangleright c_k = \text{cost of waiting for job } k$
 - $ightarrow q_{k,n,m} =
 m probability$ to move from condition n to m
 - ▷ $\mu_{k,n}$ = completion probability for job k under condition n (ordered: $\mu_{k,n} \le \mu_{k,n+1}$)
- Find a serving sequence minimizing the total cost of waiting of jobs $k \in \mathcal{K}$
- Gilbert-Elliot conditions: bad (B), good (G)

•
$$\mathcal{N}_k := \{0, B, G\}$$
, $\mathcal{A} := \{$ 'wait', 'serve' $\}$

• 0 = 'completed' ; n = 'waiting' and condition is n

• Expected one-period reward

$$egin{aligned} R_{k,0}^{ ext{`serve'}} &:= 0, & R_{k,n}^{ ext{`serve'}} &:= -c_k(1-\mu_{k,n}), \ R_{k,0}^{ ext{`wait'}} &:= 0, & R_{k,n}^{ ext{`wait'}} &:= -c_k; \end{aligned}$$

One-period transition probability matrices

$$oldsymbol{P}_k^{ ext{`serve'}} := egin{array}{cccc} 0 & B & G \ 1 & 0 & 0 \ \mu_{k,B} & \widetilde{\mu}_{k,B}q_{k,B,B} & \widetilde{\mu}_{k,B}q_{k,B,G} \ G & \mu_{k,G} & \widetilde{\mu}_{k,G}q_{k,G,B} & \widetilde{\mu}_{k,G}q_{k,G,G} \end{array} egin{array}{ccccc} \end{array}$$

- Generalized Potential improvement index
- Under discounted criterion:

$$\nu_{k,G}^* = \frac{c_k \mu_{k,G}}{(1-\beta)}, \quad \nu_{k,B}^* = \frac{c_k \mu_{k,B}}{(1-\beta) + \beta q_{k,B,G}^*(\mu_{k,G} - \mu_{k,B})}$$

$$q_{k,B,G}^{*} := \frac{1}{\frac{1 - \beta(1 - \mu_{k,G})}{q_{k,B,G}} + \frac{\beta(1 - \mu_{k,G})}{q_{k,G}^{\mathsf{SS}}}}$$

• J. (2011), IFIP Performance

• Varied $\mu_{1,B}$, while $\mu_{1,G} = 1$



• Job/user
$$k \in \mathcal{K}$$
 is defined by

 $\triangleright c_k = \text{cost of waiting for job } k$

 $\triangleright q_{k,n} =$ probability to move to condition n

 $\triangleright \mu_{k,n} =$ completion prob. for job k under condition n

 $\triangleright d_k$ = abandonment penalty for job k

 $\triangleright \theta_k = abandonment probability for job k$

• Find a serving sequence minimizing the total cost of waiting and abandonment penalties of jobs $k \in \mathcal{K}$

•
$$\mathcal{N}_k := \{0, 1, 2, \dots, N_k\}$$
, $\mathcal{A} := \{$ 'wait', 'serve' $\}$

▷ 0 = 'completed or abandoned';
n = 'waiting' and condition is n

• Expected one-period reward

$$egin{aligned} R_{k,0}^{ ext{`serve'}} &:= 0, & R_{k,n}^{ ext{`serve'}} &:= -c_k(1-\mu_{k,n}), \ R_{k,0}^{ ext{`wait'}} &:= 0, & R_{k,n}^{ ext{`wait'}} &:= -c_k(1- heta_k) - d_k heta_k; \end{aligned}$$

• One-period transition probability matrices

- A new (opportunistic) index
- Under time-average criterion:

$$\nu_{k,n}^{\mathsf{PIA}} = \frac{c_k(\mu_{k,n} - \theta_k) + d_k \theta_k \left(\mu_{k,n} + \sum_{m>n} q_{k,m}(\mu_{k,m} - \mu_{k,n})\right)}{\theta_k + \sum_{m>n} q_{k,m}(\mu_{k,m} - \mu_{k,n})}$$

• Recovers PI and AJN indices

• Varied λ_1 so that ϱ varies from 0.5 to 0.75



Conclusion

• Rich framework to study scheduling problems

- > obtain elegant index rules
- index policies optimal for relaxations
- suggests structure of (asymptotically) optimal policies

• Weakness

- no stability/optimality results
- Open problems
 - non-geometric job sizes
 - ▷ optimal solution (structure)
 - correlation among users

Thank you for your attention

Dynamic Prices (Index Values)

- We will assign a dynamic price to each user
- Arises in the solution of the parametric subproblem
 ▷ optimal policy: use server iff price greater than *ν*
- Prices are values of ν when optimal solution changes
- However, such prices may not exist!
 indexability has to be proved
- Price computation (if they exist):
 - in general, by parametric simplex method
 - by analysis sometimes obtained in a closed form

Optimal Solution to Subproblems

- For finite-state finite-action MDPs there exists an optimal policy that is deterministic, stationary, and independent of the initial state
 - ▷ we narrow our focus to those policies
 - \triangleright represent them via serving sets $\mathcal{S} \subseteq \mathcal{N}$
 - $\triangleright \text{ policy } \mathcal{S} \text{ prescribes to serve in states in } \mathcal{S} \text{ and wait in states in } \mathcal{S}^{\mathsf{C}} := \mathcal{N} \setminus \mathcal{S}$
- Combinatorial ν -cost problem: $\max_{\mathcal{S} \subseteq \mathcal{N}} \mathbb{R}_n^{\mathcal{S}} \nu \mathbb{W}_n^{\mathcal{S}}$, where

$$\mathbb{R}_{n}^{\mathcal{S}} := \mathbb{E}_{n}^{\mathcal{S}} \left[\sum_{t=0}^{\infty} \beta^{t} R_{X(t)}^{a(t)} \right], \quad \mathbb{W}_{n}^{\mathcal{S}} := \mathbb{E}_{n}^{\mathcal{S}} \left[\sum_{t=0}^{\infty} \beta^{t} W_{X(t)}^{a(t)} \right]$$

Geometric Interpretation

- $(\mathbb{W}_n^{\mathcal{S}}, \mathbb{R}_n^{\mathcal{S}})$ gives rise to 2-dim. performance region
- Indexability means the performance region is convex
- Optimal (threshold) policies are extreme points of the upper boundary of the performance region
- Index values are slopes of the upper boundary
- Indexability is sort of a dual concept to threshold policies
 - ▷ but not equivalent!



 $\mathbb{W}^{\mathcal{S}}$



 $\mathbb{W}^{\mathcal{S}}$



 $\mathbb{W}^{\mathcal{S}}$





