

Simulation and Optimisation of Queueing Systems

Jimmy Lin¹ Robert Lambert²

¹University of Glasgow

²Lancaster University



Motivation



Figure 1: Tesco Queue

Why Queues?

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Our goal is to be able to accurately model these queues, in hopes that we are able to optimise the system.

Why Simulation?

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- As a result, we propose the usage of **simulations** as an approach to model queueing systems.

Queueing Theory Introduction

Distribution and Kendall's Notation

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- Arrival Process: $X_t \sim \text{Poi}(\lambda)$
- Departure Process: $Y_t \sim \text{Exp}(\mu)$

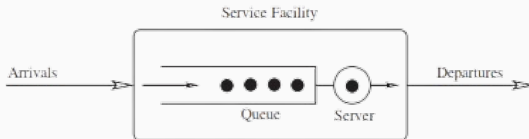
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A key feature of these distributions are that they are **memoryless** processes.

Hence, a system with one server would be denoted using Kendall's notation as an **M/M/1** queue.



Markov Chain

The state of the queues can also be modelled similar to that of a continuous time Markov Chain.

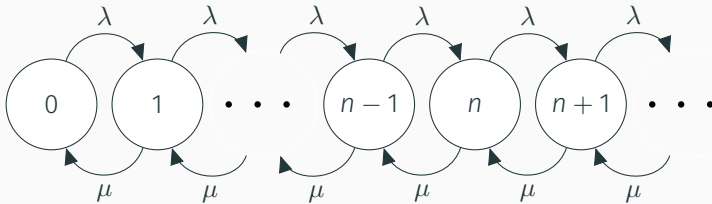


Figure 2: Markov Chain Representation of Queue States

M/M/1 Queue

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- This interarrival time is distributed by an **exponential distribution**.

Simulation of M/M/1 Queues

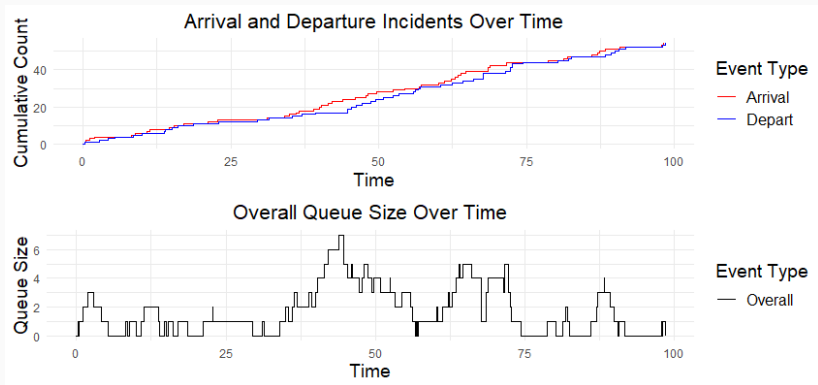


Figure 3: Queueing Simulation with $\lambda = 0.6$ and $\mu = 0.8$ up to $t = 100$

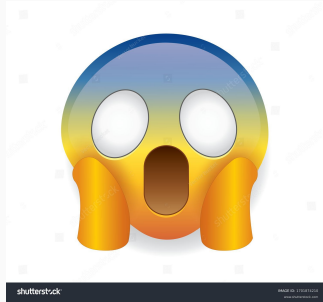
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Steady State Solution

In an M/M/1 queue when $\lambda < \mu$, we have the closed form steady state solution:

$$p_n = (1 - \rho)\rho^n, \quad \rho = \frac{\lambda}{\mu}$$

Comparison

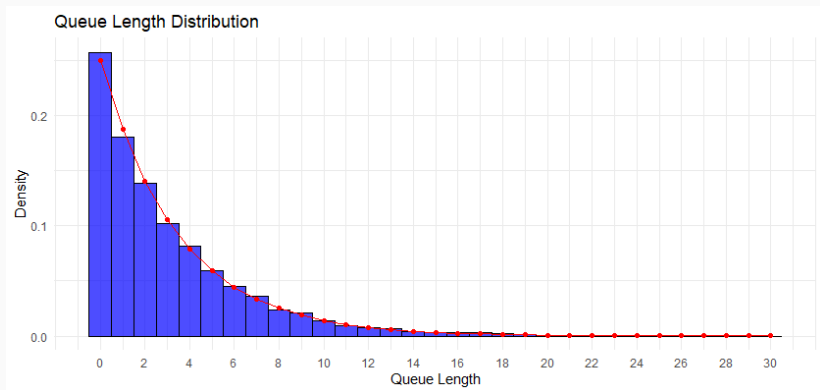


Figure 4: Density Histogram of 1000 Queue Simulations to Steady State Solution

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- Impatient Customers
- Scheduling Disciplines
- Group arrivals and departures
- and many more...

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Today, we will look at the issue of non-constant arrival rate.

M(t)/M/1 Queue

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What could be the issues with an inhomogeneous poisson process?

- Now the **interarrival time** will **not** necessarily be exponentially distributed. Could simulation be harder?
- With varying transitional properties, this makes the problem an **inhomogeneous process**, hence a **steady state solution** will likely **not** be available.

Thinning Algorithm

- We simulate a **homogeneous queue** with an arrival rate of $\bar{\lambda} = \sup_t \lambda(t)$.
- For each arrival, we want to **accept the arrival** with **probability**:

$$\mathbb{P}\{\text{Accept Arrival}\} = \frac{\lambda(t)}{\bar{\lambda}}$$

where t represents the time in which the arrival at rate $\bar{\lambda}$ has occurred.

This is what is known as a thinning algorithm.

Thinning Algorithm

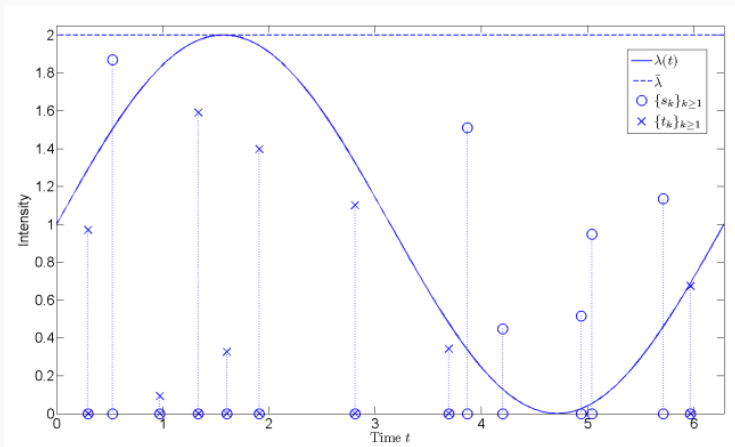


Figure 5: Thinning algorithm [Chen, 2016]

Inhomogeneous Poisson Process

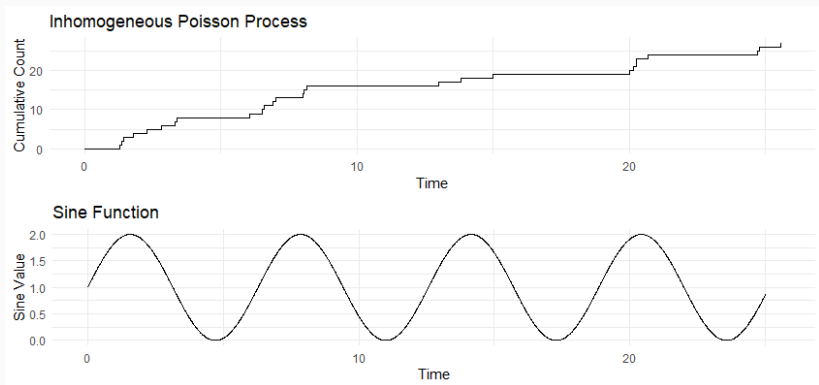


Figure 6: Inhomogeneous Poisson Process with $\lambda(t) = \sin(t) + 1$

Due to a lack of steady state solution, we use **numerical** integration for the comparison of our simulation.

Notation used:

$$p_n(t) = \mathbb{P}\{n \text{ in state at time } t\}$$

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2. Apply classical queueing theory model for the next time step:

$$\begin{aligned}p_n(t + d) &= \lambda(t)d p_{n-1}(t) + [1 - \lambda(t)d - \mu d] p_n(t) + \mu d p_{n+1}(t) \\p_0(t + d) &= [1 - \lambda(t)d] p_0(t) + \mu d p_1(t) \\p_{n_{\max}}(t + d) &= \lambda(t)d p_{n_{\max}-1} + [1 - \mu d] p_{n_{\max}}\end{aligned}\tag{1}$$

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3. Increment time point: $t = t + d$
4. Repeat until you reach maximum time.

To compare the results, we use **average system length** of both simulation and numerical integration result.

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We use this formula to calculate average system length of queue.

$$L(t) = \sum_{n=0}^{n_{\max}} np_n(t)$$

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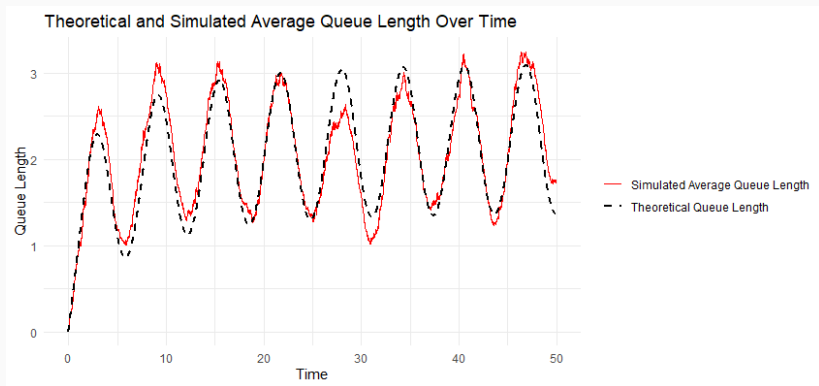


Figure 7: $M(t)/M/1$ Average System Length

Queue Extensions



Figure 8: Taxi Queue in Ibiza

Double-ended Queues

One of the extensions we looked at was double-ended queueing systems.

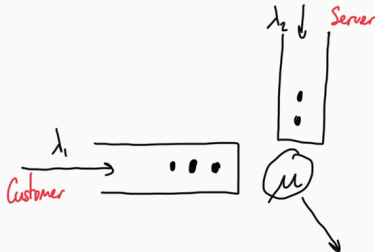


Figure 9: Double-Ended Queueing System

Simulation

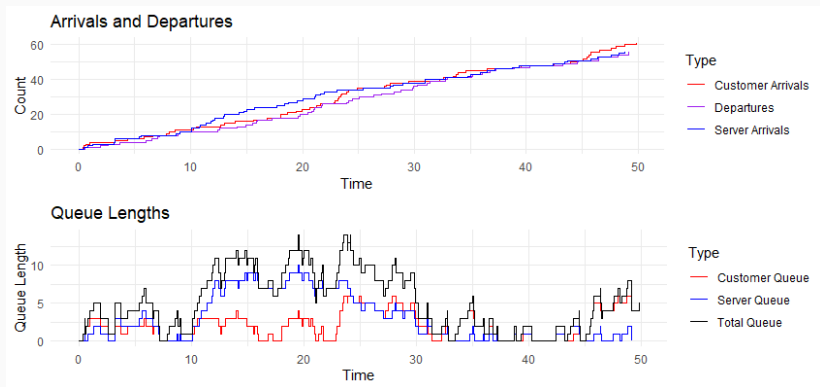


Figure 10: Simulation of a double-ended queue with $\lambda_1 = \lambda_2 = 1$ and $\mu = 2$.

Sanity Check

With $\mu \rightarrow \infty$, one side of the queue will always be empty.

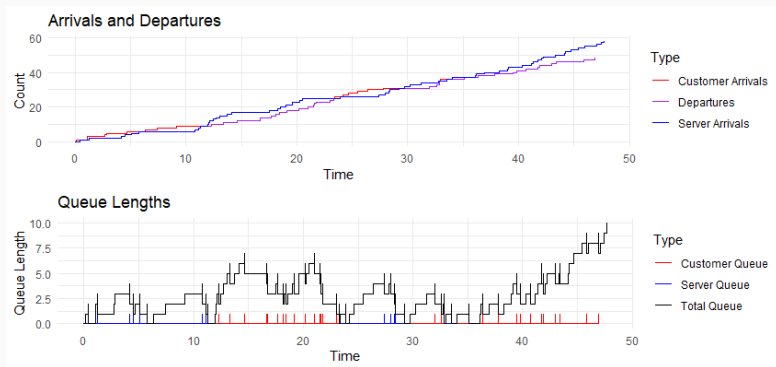


Figure 11: Simulation of a double-ended queue with $\lambda_1 = \lambda_2 = 1$ and $\mu = 10000$

Decision Making - Optimisation

- Target variable is λ .
- We want to optimise to a certain objective denoted $F(\lambda)$.
- An example can be within an M/M/1 queue where we maximise entry with respect to a cost of waiting time.
- Typically in reality, we will also require observations of our service time to complete this $\hat{\mu}$.

Steps to Optimisation

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2. Use the MLE to estimate the departure parameter μ .
3. Simulate the queue over a selected set of λ s.
4. Choose $\lambda_t^* = \arg \max_{\lambda} F(\lambda)$. Set the next cycle $\lambda_{t+1} = \lambda_t^*$.

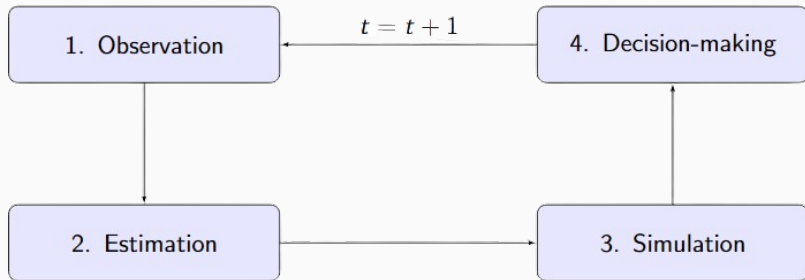


Figure 12: Simulation Optimisation Flow Chart

Decision-making assumptions made:

- At t_{\max} , the queue **no longer accepts entries** but the simulation **continues until all customers are served**.
- Without this, computation may be more difficult as it would skew rate $\hat{\mu}$ upwards and average waiting time downwards.

Example Setup

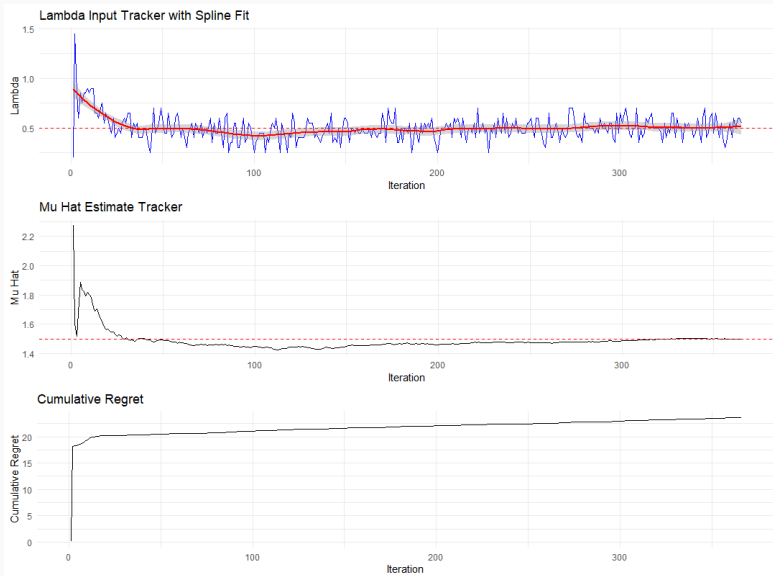
- Begin with $\lambda_0 = 0.2$ and true $\mu = 1.5$.
- Cycle through 24 time units per cycle for 365 cycles.
- 40 (week long) simulations for each λ when optimising.
- Objective function is set as:

$$F(\lambda) = \frac{\text{\#arrivals}}{t_{\max}} - \frac{\sum_{i=1}^n w_i}{n}$$

- The steady state equivalent for this is

$$F(\lambda) = \lambda - \frac{\lambda}{\mu(\mu - \lambda)}$$

Example Optimisation



Pros

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Cons

- Computationally slow with more complex systems.
- Does not settle on a solution and constantly fluctuates (hence the need for splines for understandability).

Conclusion

- Improve computational time for simulations.
- Develop simulations for more advanced queues with less assumptions, i.e. multi-server queue
- Develop optimisations for more advanced queues, i.e. double-ended taxi queues.
- Explore further simulation optimisation methodologies.

References



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Any questions?

Me: raises my hand



the teacher:



Appendix

Proof: Poisson Arrival Implies Exponential Interarrival

Let T_n and T_{n-1} denote the time difference between two arrivals, i.e. the interarrival time, and $p_n(t) = \frac{(\lambda t)^n}{n!} \exp(-\lambda t)$.

$$\begin{aligned} F(t) &= \mathbb{P}(T_n - T_{n-1} \leq t) \\ &= \mathbb{P}(T_1 \leq t) \quad \text{due to memoryless property} \\ &= \mathbb{P}\{\text{at least one event occurred } (0, t]\} \\ &= 1 - \mathbb{P}\{\text{no event occurred } (0, t]\} \\ &= 1 - p_0(t) \\ &= 1 - \exp(-\lambda t) \end{aligned} \tag{2}$$

Hence obtaining the PDF, we can differentiate $F(t)$

$$f(t) = \frac{dF(t)}{dt} = \lambda \exp(-\lambda t)$$

Which is the PDF for the exponential distribution.

Alternative Objective Functions

Objective functions can be chosen to suit needs of decision maker.

Examples:

- Maintain unit of time by replacing arrival count with interarrival time.

$$F(\lambda) = -\frac{1}{\lambda} - \frac{\lambda}{\mu(\mu - \lambda)}$$

- Adjust severeness of reward or cost of existing objective function by α and β .

$$F(\lambda) = \alpha\lambda - \beta \left(\frac{\lambda}{\mu(\mu - \lambda)} \right)$$