

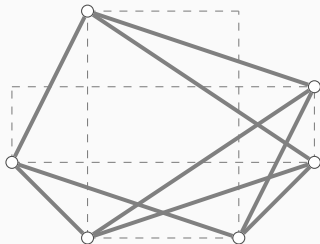
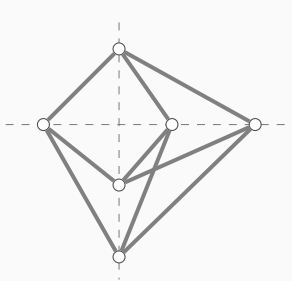
On the Classification of Motions of Laman Graphs

Georg Grasegger, Jan Legerský, Josef Schicho

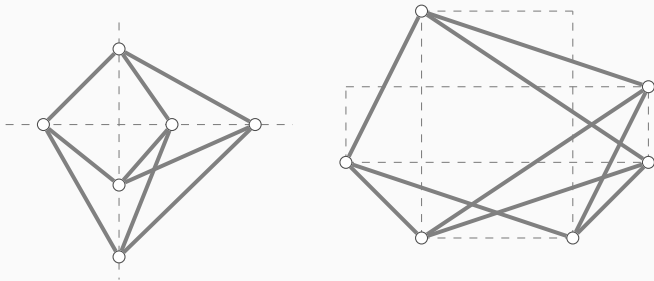
RISC JKU Linz, Austria

Geometric constraint systems: rigidity, flexibility and applications
Lancaster, UK, June 12, 2019

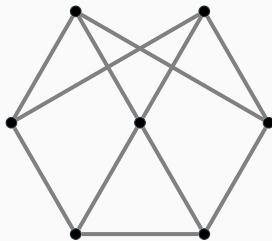




Dixon (1899), Walter and Husty (2007)



Dixon (1899), Walter and Husty (2007)



Q_1

Proper flexible labelings

An edge labeling $\lambda : E \rightarrow \mathbb{R}_+$ of a graph $G = (V, E)$ is called *flexible* if there are infinitely many non-congruent realizations $\rho : V \rightarrow \mathbb{R}^2$ such that $\|\rho(u) - \rho(v)\| = \lambda(uv)$ for all edges uv in E .

$$(x_{\bar{u}}, y_{\bar{u}}) = (0, 0)$$

$$(x_{\bar{v}}, y_{\bar{v}}) = (\lambda(\bar{u}\bar{v}), 0)$$

$$(x_u - x_v)^2 + (y_u - y_v)^2 = \lambda(uv)^2, \quad \forall uv \in E$$

An irreducible component of the solution set is called an *algebraic motion*.

Proper flexible labelings

An edge labeling $\lambda : E \rightarrow \mathbb{R}_+$ of a graph $G = (V, E)$ is called *proper flexible* if there are infinitely many non-congruent *injective* realizations $\rho : V \rightarrow \mathbb{R}^2$ such that $\|\rho(u) - \rho(v)\| = \lambda(uv)$ for all edges uv in E .

$$(x_{\bar{u}}, y_{\bar{u}}) = (0, 0)$$

$$(x_{\bar{v}}, y_{\bar{v}}) = (\lambda(\bar{u}\bar{v}), 0)$$

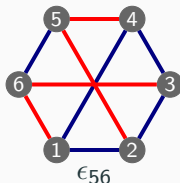
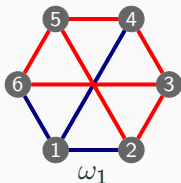
$$(x_u - x_v)^2 + (y_u - y_v)^2 = \lambda(uv)^2, \quad \forall uv \in E$$

$$(x_u - x_v)^2 + (y_u - y_v)^2 \neq 0, \quad \forall uv \notin E.$$

NAC-colorings

Definition

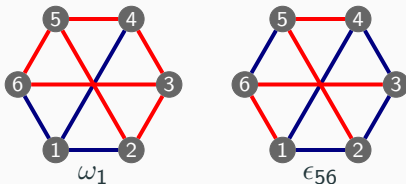
A coloring of edges $\delta : E \rightarrow \{\text{blue, red}\}$ is called a *NAC-coloring*, if it is surjective and for every cycle in G , either all edges in the cycle have the same color, or there are at least two blue and two red edges in the cycle.



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Theorem (GLS)

A connected graph with at least one edge has a flexible labeling if and only if it has a NAC-coloring.

$$\begin{aligned}\lambda_{uv}^2 &= (x_v - x_u)^2 + (y_v - y_u)^2 \\ &= \underbrace{((x_v - x_u) + i(y_v - y_u))}_{W_{u,v}} \underbrace{((x_v - x_u) - i(y_v - y_u))}_{Z_{u,v}}\end{aligned}$$

Lemma (GLS)













Let λ be a flexible labeling of a graph G . Let \mathcal{C} be an algebraic motion of (G, λ) . If $\alpha \in \mathbb{Q}$ and ν is a valuation of the complex function field of \mathcal{C} such that there exists edges $\bar{u}\bar{v}, \hat{u}\hat{v}$ with $\nu(W_{\bar{u},\bar{v}}) = \alpha$ and $\nu(W_{\hat{u},\hat{v}}) > \alpha$, then $\delta : E_G \rightarrow \{\text{red}, \text{blue}\}$ given by

$$\delta(uv) = \text{red} \iff \nu(W_{u,v}) > \alpha,$$

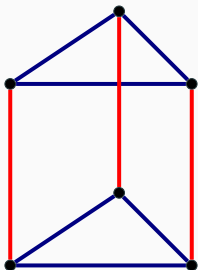
$$\delta(uv) = \text{blue} \iff \nu(W_{u,v}) \leq \alpha.$$

is a NAC-coloring, called *active*.

Active NAC-colorings of quadrilaterals

Quadrilateral	Motion	Active NAC-colorings
Rhombus	parallel degenerate	  resp. 
Parallelogram		
Antiparallelogram		 
Deltoid	nondegenerate degenerate	  
General		  

Three-prism



Leading coefficient system

Assume a valuation that gives only one active NAC-coloring
 \implies Laurent series parametrization.

For every cycle $C = (u_1, \dots, u_n)$:

$$\sum_{\substack{i \in \{1, \dots, n\} \\ \delta(u_i u_{i+1}) = \text{red}}} \underbrace{(w_{u_i u_{i+1}} t + \text{h.o.t.})}_{W_{u_i, u_{i+1}}} + \sum_{\substack{i \in \{1, \dots, n\} \\ \delta(u_i u_{i+1}) = \text{blue}}} \underbrace{(w_{u_i u_{i+1}} + \text{h.o.t.})}_{W_{u_i, u_{i+1}}} = 0.$$

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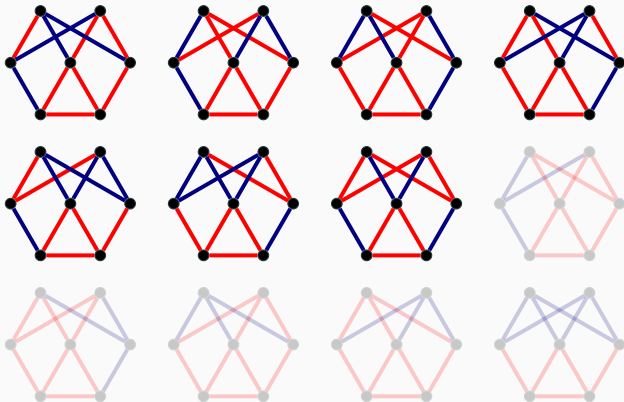
For all $uv \in E_G$:

$$w_{uv} z_{uv} = \lambda_{uv}^2.$$

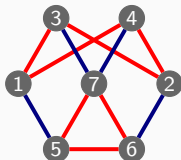
\implies elimination using Gröbner basis provides an equation in λ_{uv} 's.

Singleton NAC-colorings

If a valuation yields two active NAC-colorings δ, δ' , then the set $\{(\delta(e), \delta'(e)) : e \in E_G\}$ has 3 elements.



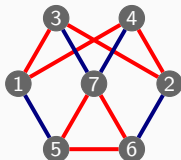
Triangle in Q_1



$$\implies \lambda_{57}^2 r^2 + \lambda_{67}^2 s^2 + (\lambda_{56}^2 - \lambda_{57}^2 - \lambda_{67}^2) rs = 0,$$

$$r = \lambda_{24}^2 - \lambda_{23}^2, s = \lambda_{14}^2 - \lambda_{13}^2$$

Triangle in Q_1

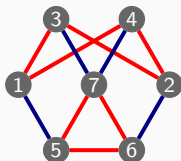


$$\implies \lambda_{57}^2 r^2 + \lambda_{67}^2 s^2 + (\lambda_{56}^2 - \lambda_{57}^2 - \lambda_{67}^2) rs = 0,$$

$$r = \lambda_{24}^2 - \lambda_{23}^2, s = \lambda_{14}^2 - \lambda_{13}^2$$

Considering the equation as a polynomial in r , the discriminant is $(\lambda_{56} + \lambda_{57} + \lambda_{67})(\lambda_{56} + \lambda_{57} - \lambda_{67})(\lambda_{56} - \lambda_{57} + \lambda_{67})(\lambda_{56} - \lambda_{57} - \lambda_{67})s^2$.

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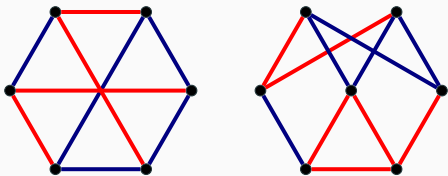
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Theorem (GLS)

The vertices 5, 6 and 7 are collinear for every proper flexible labeling of Q_1 .

Orthogonal diagonals



Lemma (GLS)

If there is an active NAC-coloring δ of an algebraic motion of (G, λ) such that a 4-cycle $(1, 2, 3, 4)$ is blue and there are red paths from 1 to 3 and from 2 to 4, then

$$\lambda_{12}^2 + \lambda_{34}^2 = \lambda_{23}^2 + \lambda_{14}^2,$$

namely, the 4-cycle $(1, 2, 3, 4)$ has orthogonal diagonals.

Ramification formula

Theorem (GLS)

Let \mathcal{C} be an algebraic motion of (G, λ) with the set of active NAC-colorings N . There exists $\mu_\delta \in \mathbb{Z}_{\geq 0}$ for all NAC-colorings δ of G such that:

1. $\mu_\delta \neq 0$ if and only if $\delta \in N$, and
2. for every 4-cycle (V_i, E_i) of G , there exists a positive integer d_i such that

$$\sum_{\substack{\delta \in \text{NAC}_G \\ \delta|_{E_i} = \delta'}} \mu_\delta = d_i \quad \text{for all } \delta' \in \{\delta|_{E_i} : \delta \in N\}.$$

Ramification formula

Theorem (GLS)

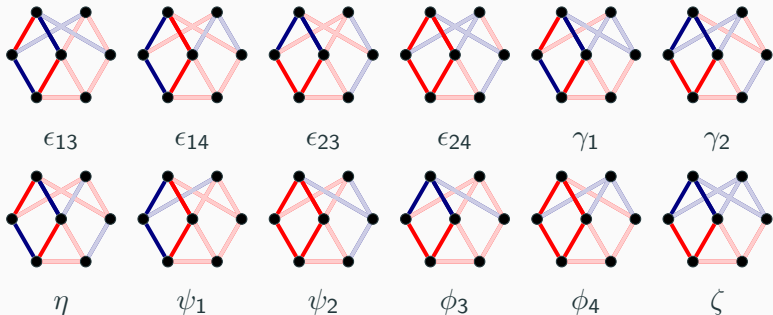
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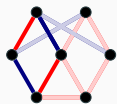
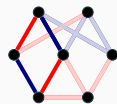
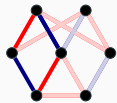
$$\begin{aligned} \mathfrak{p} &= \left\{ \begin{array}{|c|} \hline \color{red}\square \\ \hline \color{blue}\square \\ \hline \end{array} \right\}, & \mathfrak{o} &= \left\{ \begin{array}{|c|} \hline \color{red}\square, \color{blue}\square \\ \hline \end{array} \right\}, & \mathfrak{g} &= \left\{ \begin{array}{|c|} \hline \color{red}\square, \color{blue}\square, \color{red}\square \\ \hline \end{array} \right\}, \\ \mathfrak{a} &= \left\{ \begin{array}{|c|} \hline \color{red}\square, \color{blue}\square \\ \hline \end{array} \right\}, & \mathfrak{e} &= \left\{ \begin{array}{|c|} \hline \color{red}\square, \color{blue}\square \\ \hline \end{array} \right\}. \end{aligned}$$

Example



Antiparallelogram $\left(\begin{array}{|c|} \hline \square \\ \hline \end{array}, \begin{array}{|c|} \hline \square \\ \hline \end{array} \right) \implies$

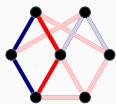
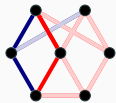
Example


 ϵ_{13}
 ϵ_{14}
 ϵ_{23}
 ϵ_{24}

 γ_1
 γ_2

 η
 ψ_1
 ψ_2
 ϕ_3
 ϕ_4
 ζ

Antiparallelogram $\left(\begin{array}{|c|} \hline \square \\ \hline \end{array}, \begin{array}{|c|} \hline \square \\ \hline \end{array} \right) \implies$

$$\mu_{\epsilon_{13}} = \mu_{\gamma_1} = \mu_{\eta} = 0$$

Example

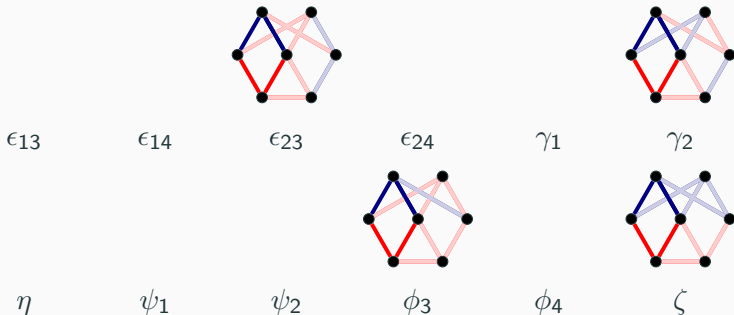

 ϵ_{13}
 ϵ_{14}
 ϵ_{23}
 ϵ_{24}
 γ_1
 γ_2

 η
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 ϕ_3
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 ζ

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$$\mu_{\epsilon_{14}} + \mu_{\psi_1}$$

Example



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$$\mu_{\epsilon_{13}} = \mu_{\gamma_1} = \mu_{\eta} = 0$$

$$\mu_{\epsilon_{14}} + \mu_{\psi_1} = \mu_{\epsilon_{23}} + \mu_{\gamma_2} + \mu_{\phi_3} + \mu_{\zeta}$$

Classification of motions

- Find all possible types of motions of quadrilaterals with consistent μ_δ 's

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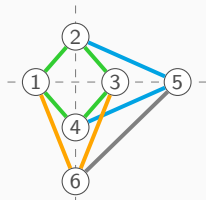
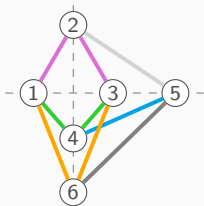
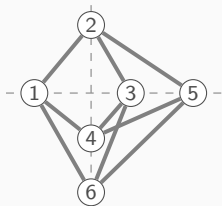
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Implementation – SageMath package FlexRiLoG
(<https://github.com/Legersky/flexrilog>)



4-cycles

active NAC-colorings

#

gggggggggg

$\text{NAC}_{K_{3,3}}$

1

oooggggggg

$\{\epsilon_{12}, \epsilon_{23}, \epsilon_{34}, \epsilon_{14}, \epsilon_{16}, \epsilon_{36}, \omega_1, \omega_3\}$

6

Dixon I

pooggogge

$\{\epsilon_{12}, \epsilon_{23}, \epsilon_{34}, \epsilon_{14}\}$

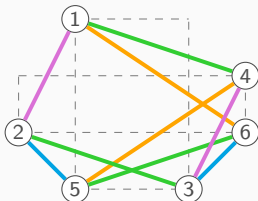
9

pgggaggag

$\{\epsilon_{12}, \epsilon_{34}, \omega_5, \omega_6\}$

18

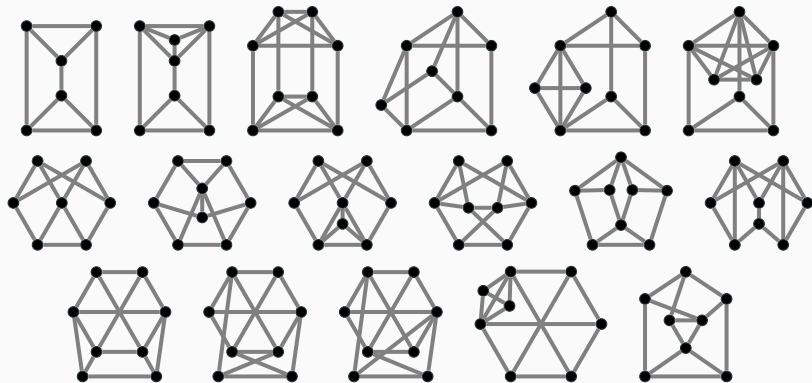
Dixon II



Classification of motions of Q_1

4-cycles	active NAC-colorings	#	type	dim.
pggpgpg	$\{\epsilon_{13}, \epsilon_{24}, \eta\}$	2	I	4
poapope	$\{\epsilon_{13}, \eta\}$	4	\subset I, IV ₋ , V, VI	2
pe epapa	$\{\epsilon_{13}, \epsilon_{24}\}$	2	\subset I, II, III	2
ogggggg	$\{\epsilon_{ij}, \gamma_1, \gamma_2, \psi_1, \psi_2\}$	1	II ₋ \cup II ₊	5
pe egggg	$\{\epsilon_{13}, \epsilon_{14}, \epsilon_{23}, \epsilon_{24}\}$	1	\subset II ₋ , II ₊	4
oggp gga	$\{\epsilon_{13}, \epsilon_{24}, \gamma_1, \psi_2\}$	4	\subset II ₋	3
ogge gge	$\{\epsilon_{13}, \epsilon_{23}, \gamma_1, \gamma_2\}$	2	\subset II ₋ , deg.	2
ogggaga	$\{\epsilon_{13}, \epsilon_{24}, \psi_1, \psi_2, \zeta\}$	2	III	3
ggapggg	$\{\epsilon_{13}, \eta, \phi_4, \psi_2\}$	4	IV ₋ \cup IV ₊	4
ggaegpe	$\{\epsilon_{13}, \eta, \gamma_2, \phi_3\}$	4	V	3
pgge gge	$\{\epsilon_{13}, \epsilon_{23}, \eta, \zeta\}$	2	VI	3

Other graphs



Thank you

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Animations